















The Team

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Alexander Rumball 3D Design



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Josh Tanner M<u>aterials</u>







The Problem

Lack of Mobility

- 1 in 3 over 65 have difficulty.
- Walking, standing, steps etc.
- Researched current mobility assistive devices.

Gantry Hoists

- · Initially focused and researched
- · Really well developed.

Mission Statement
"We need to design and create a solution that
will allow the safe
moving of patients who have reduced mobility. It
must not impose too much work on both
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Zimmer Frames

- Basic and more advanced options.
- Scope for further development.
- What could be changed?





New Solution, Why?

- Make the Zimmer Frame more mobile.
- Reduce user's fatigue and therefore increase mobility
- Reduce social impacts.
 - "I can go for days without hearing from my family"

Refined Mission

retro fit or new Zimmer frame to assist/ ease in the safe movement of a person of the aging population."





Refined Mission Statement

"We want to design a retro fit or new Zimmer frame to assist/ ease in the safe movement of a person of the aging population."



The Zoomerframe







Ultrasonics



Power Source



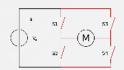
Motorized wheels



How it works



Ultrasonic sensor sends out sound waves and waits for an echo



The arduino tells the H-Bridge what speed to turn the motors



Ardunino receives signal and converts time to distance

Emergency Stop!



Push to make switch mounted in the handles.

Wheels start turning









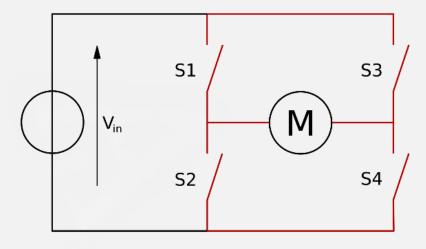
Ultrasonic sensor sends out sound waves and waits for an echo





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Wheels start turning





Better Mobility!





Emergency Stop!



Push to make switch mounted in the handles.



Why it works:

- Tests in the lab showed the full system functioning properly.
- The frame is stable and unlikely to topple.
- No lifting required.
- Reduced user fatigue.

Why is it better?!

- Retrofit system.
 - Parts can be easily sourced.
 - · Low cost.
 - Increased mobility







"Our improved design eliminates the awkward clumsiness of zimmer frames, using ultrasonic sensors to detect presence in the frame and communicate with the motors using Arduino to drive the frame."

